

On triple systems and extended Dynkin diagrams of Lie superalgebras ¹

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Abstract

Our aim is to give a characterization of extended Dynkin diagrams of Lie superalgebras by means of concept of triple systems.

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1 Preliminaries and examples

Throughout this paper, we shall be concerned with algebras and triple systems over a field Φ that is characteristic not 2 and do not assume that our algebras and triple systems are finite dimensional, unless otherwise specified.

Definition 1.1. For $\varepsilon = \pm 1$ and $\delta = \pm 1$, a vector space $U(\varepsilon, \delta)$ over Φ with the triple product $\langle -, -, - \rangle$ is called a (ε, δ) -Freudenthal–Kantor triple system if

$$\begin{aligned} [L(a, b), L(c, d)] &= L(\langle abc \rangle, d) + \varepsilon L(c, \langle bad \rangle) \\ K(\langle abc \rangle, d) + K(c, \langle abd \rangle) + \delta K(a, K(c, d)b) &= 0 \end{aligned}$$

where

$$L(a, b)c = \langle abc \rangle, \quad K(a, b)c = \langle acb \rangle - \delta \langle bca \rangle, \quad [A, B] = AB - BA$$

Remark 1.1. We note that

$$\begin{aligned} S(a, b) &:= L(a, b) + \varepsilon L(b, a) \\ A(a, b) &:= L(a, b) - \varepsilon L(b, a) \end{aligned}$$

are a derivation and an anti-derivation of $U(\varepsilon, \delta)$, respectively.

Definition 1.2. A (ε, δ) -Freudenthal–Kantor triple system over Φ is said to be *balanced* if

$$\dim_{\Phi} \{K(x, y)\}_{\text{span}} = 1$$

Definition 1.3. For $\delta = \pm 1$, a triple system over Φ is said to be δ -Lie triple system if the following are satisfied:

$$\begin{aligned} [abc] &= -\delta[bac] \\ [abc] + [bca] + [cab] &= 0 \\ [ab[cde]] &= [[abc]de] + [c[abd]e] + [cd[abe]] \end{aligned}$$

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For the δ -Lie triple systems associated with (ε, δ) -Freudenthal–Kantor triple systems, we have the following.

Proposition 1.1 ([7]). *Let $U(\varepsilon, \delta)$ be a (ε, δ) -Freudenthal–Kantor triple system. If P is a linear transformation of $U(\varepsilon, \delta)$ such that $P \langle xyz \rangle = \langle PxPyPz \rangle$ and $P^2 = -\varepsilon\delta \text{Id}$, then $(U(\varepsilon, \delta), [-, -, -])$ is a Lie triple system for the case of $\delta = 1$ and an anti-Lie triple system for the case of $\delta = -1$ with respect to the product*

$$[xyz] := \langle xPyz \rangle - \delta \langle yPxz \rangle + \delta \langle xPzy \rangle - \langle yPzx \rangle$$

Corollary 1.1. *Let $U(\varepsilon, \delta)$ be a (ε, δ) -Freudenthal–Kantor triple system. Then the vector space $T(\varepsilon, \delta) := U(\varepsilon, \delta) \oplus U(\varepsilon, \delta)$ becomes a Lie triple system for the case of $\delta = 1$ and an anti-Lie triple system for the case of $\delta = -1$ with respect to the triple product defined by*

$$\left[\begin{pmatrix} a \\ b \end{pmatrix} \begin{pmatrix} c \\ d \end{pmatrix} \begin{pmatrix} e \\ f \end{pmatrix} \right] = \begin{pmatrix} L(a, d) - \delta L(c, b) & \delta K(a, c) \\ -\varepsilon K(b, d) & \varepsilon(L(d, a) - \delta L(b, c)) \end{pmatrix} \begin{pmatrix} e \\ f \end{pmatrix}$$

From these results, it follows that the vector space

$$L(V) := \text{Inn Der } T \oplus T (= L(T, T) \oplus T)$$

where T is a δ -Lie triple system and $\text{Inn Der } T := \{L(X, Y) | X, Y \in T\}_{\text{span}}$ turns out to be a Lie algebra ($\delta = 1$) or Lie superalgebra ($\delta = -1$) by

$$[D + X, D' + X'] = [D, D'] + L(X, X') + DX' - D'X$$

Definition 1.4. We denote by $L(\varepsilon, \delta)$ the Lie algebras or Lie superalgebras obtained from these constructions associated with $U(\varepsilon, \delta)$ and call these algebras a *canonical standard embedding*.

Definition 1.5. A (ε, δ) -Freudenthal–Kantor triple system $U(\varepsilon, \delta)$ is said to be *unitary* if the linear span \mathbf{k} of the set $\{K(a, b) | a, b \in U(\varepsilon, \delta)\}$ contains the identity endomorphism Id .

Remark 1.2. We note that the balanced property is unitary.

For these standard embedding Lie algebras or superalgebras $L(\varepsilon, \delta)$, we have the following 5 grading subspaces:

$$L(\varepsilon, \delta) = L_{-2} \oplus L_{-1} \oplus L_0 \oplus L_1 \oplus L_2$$

where

$$U(\varepsilon, \delta) = L_{-1}, \quad T(\varepsilon, \delta) = L_{-1} \oplus L_1, \quad \mathbf{k} = \{K(a, b)\}_{\text{span}} = L_{-2}$$

2 Lie superalgebras $D(2, 1; \alpha)$, $G(3)$ and $F(4)$

These constructions of $D(2, 1, \alpha)$, $G(3)$ and $F(4)$ are considered [8, 1]. Briefly describing, we have the following.

1. *Let V be a quaternion algebra over the complex numbers. Then V is a balanced $(-1, -1)$ Freudenthal–Kantor triple system with respect to certain triple product and the standard embedding Lie superalgebra $L(U)$ is $D(2, 1; \alpha)$ type's with $\dim L(V) = 17$.*
2. *Let V be an octonion algebra over the complex number. Then V is a balanced $(-1, -1)$ Freudenthal–Kantor triple system with respect to certain triple product and the standard embedding Lie superalgebra $L(U)$ is $F(4)$ type's with $\dim L(V) = 40$.*
3. *Let V be a $\text{Im } \mathbb{O}$ (= the imaginary part of octonion algebra). Then V is a balanced $(-1, -1)$ -Freudenthal–Kantor triple system with respect to certain triple product and the standard embedding Lie superalgebra $L(U)$ is $G(3)$ type's with $\dim L(V) = 31$.*

3 Extended Dynkin diagrams and triple systems

In this section, we will only describe about distinguished extended Dynkin diagram of their canonical Lie superalgebras associated with $(-1, -1)$ -Freudenthal–Kantor triple systems $F(4)$ and $G(3)$ types, because for the other cases we may deal with the explanation by means of the same methods.

(a) For $F(4)$ type distinguished extended Dynkin diagram and usual Dynkin diagram [3] we have the following:

$$\begin{array}{ccccccccc} \bigcirc & \equiv & \bigotimes & - & \bigcirc & \leftarrow & \bigcirc & - & \bigcirc \\ \alpha_0 & & \alpha_1 & & \alpha_2 & & \alpha_3 & & \alpha_4 \\ \bigotimes & - & \bigcirc & \leftarrow & \bigcirc & - & \bigcirc & & \\ \alpha_1 & & \alpha_2 & & \alpha_3 & & \alpha_4 & & \end{array}$$

$U = L_{-1} = (-1, -1)$ is a balanced Freudenthal–Kantor triple system with $\dim U = 8$ (cf Sec. 2).

$$\begin{aligned} U &\leftrightarrow \begin{array}{cccc} \bigotimes & \bigcirc & \bigcirc & \bigcirc \\ & \bigcirc & \bigcirc & \\ & & \bigcirc & \end{array} \\ &\leftrightarrow \{ \alpha_1, \alpha_1 + \alpha_2, \alpha_1 + \alpha_2 + \alpha_3, \alpha_1 + \alpha_2 + \alpha_3 + \alpha_4, \alpha_1 + 2\alpha_2 + \alpha_3, \alpha_1 + 2\alpha_2 + \alpha_3 + \alpha_4, \\ &\quad \alpha_1 + 2\alpha_2 + 2\alpha_3 + \alpha_4, \alpha_1 + 3\alpha_2 + 2\alpha_3 + \alpha_4 \} \\ L_{-2}(U) &\leftrightarrow \{ 2\alpha_1 + 3\alpha_2 + 2\alpha_3 + \alpha_4 \} \end{aligned}$$

$L(U)$ is the standard embedding Lie superalgebra associated with U and $\dim L(U) = 40$, $\dim L_{-2} = \dim L_2 = 1$. Then we can easily see its structure as follows:

$$L(U)/(L_{-2} \oplus L_0 \oplus L_2) \cong L_{-1} \oplus L_1 := T \quad (\text{as anti-Lie triple system})$$

and

$$\begin{aligned} \text{Inn Der } T &\cong L_{-2} \oplus L_0 \oplus L_2 = A_1 \oplus B_3 \\ &= \text{distinguished extended Dynkin diagram with omitted } \bigotimes \\ &= \left\{ \left(\begin{array}{cc} L(a, b) & -K(c, d) \\ K(e, f) & -L(b, a) \end{array} \right) \right\}_{\text{span}} \\ L_0 &= \lambda I \oplus B_3 = \left\{ \left(\begin{array}{cc} L(a, b) & 0 \\ 0 & -L(b, a) \end{array} \right) \right\}_{\text{span}} = \{L(a, b)\}_{\text{span}} \end{aligned}$$

of course, $L(a, b) = S(a, b) + A(a, b)$, where $S(a, b)$ is a inner derivation of U , $K(a, b) = A(a, b) = \langle . | . \rangle \text{Id}$ is an anti-derivation of U .

Furthermore, these imply

$$\begin{aligned} A_1 &\cong \left\{ \left(\begin{array}{cc} 0 & \text{Id} \\ 0 & 0 \end{array} \right) \right\}_{\text{span}} \oplus \left\{ \left(\begin{array}{cc} \text{Id} & 0 \\ 0 & -\text{Id} \end{array} \right) \right\}_{\text{span}} \oplus \left\{ \left(\begin{array}{cc} 0 & 0 \\ \text{Id} & 0 \end{array} \right) \right\}_{\text{span}} \\ &= L_{-2} \oplus \{A(a, b)\}_{\text{span}} \oplus L_2 \\ \text{Inn Der } U &= \{S(a, b)\}_{\text{span}} \cong B_3 = \text{Dynkin diagram with omitted } \bigotimes \end{aligned}$$

(b) For $G(3)$ type distinguished extended Dynkin diagram and usual Dynkin diagram [3] as well as $F(4)$ we have the following:

$$\begin{array}{cccc}
 \bigcirc \equiv > \bigotimes - \bigcirc \Leftarrow \bigcirc & & & \\
 \alpha_0 & \alpha_1 & \alpha_2 & \alpha_3 \\
 \bigotimes - \bigcirc \Leftarrow \bigcirc & & & \\
 \alpha_1 & \alpha_2 & \alpha_3 &
 \end{array}$$

$U = L_{-1} = (-1, -1)$ -balanced Freudenthal–Kantor triple system with $\dim U = 7$ (cf Section 2),

$$\begin{array}{l}
 U \leftrightarrow \bigotimes \quad \bigcirc \quad \bigcirc \\
 \quad \quad \quad \bigcirc \quad \bigcirc \\
 \quad \quad \quad \bigcirc \\
 \quad \quad \quad \bigcirc \\
 \leftrightarrow \{ \alpha_1, \alpha_1 + \alpha_2, \alpha_1 + \alpha_2 + \alpha_3, \alpha_1 + 2\alpha_2 + \alpha_3, \alpha_1 + 3\alpha_2 + \alpha_3, \alpha_1 + 3\alpha_2 + 2\alpha_3, \\
 \quad \quad \quad \alpha_1 + 4\alpha_2 + 2\alpha_3 \} \\
 L_{-2}(U) \leftrightarrow \{ 2\alpha_1 + 4\alpha_2 + 2\alpha_3 \}
 \end{array}$$

$L(U)$ is the standard embedding Lie superalgebra associated with U and $\dim L(U) = 31$, $\dim L_{-2} = \dim L_2 = 1$. Then we can easily see its structure as follows:

$$L(U)/(L_{-2} \oplus L_0 \oplus L_2) \cong L_{-1} \oplus L_1 := T \quad (\text{as anti-Lie triple system})$$

and

$$\begin{aligned}
 \text{Inn Der } T &\cong L_{-2} \oplus L_0 \oplus L_2 = A_1 \oplus G_2 \\
 &= \text{distinguished extended Dynkin diagram with omitted } \otimes \\
 &= \left\{ \left(\begin{array}{cc} L(a, b) & -K(c, d) \\ K(e, f) & -L(b, a) \end{array} \right) \right\}_{\text{span}} \\
 L_0 = \lambda I \oplus B_3 &= \left\{ \left(\begin{array}{cc} L(a, b) & 0 \\ 0 & -L(b, a) \end{array} \right) \right\}_{\text{span}} = \{L(a, b)\}_{\text{span}}
 \end{aligned}$$

Of course, $L(a, b) = S(a, b) + A(a, b)$, where $S(a, b)$ is an inner derivation of U , $K(a, b) = A(a, b) = \langle \cdot, \cdot \rangle \text{Id}$ is an anti-derivation of U . Furthermore, these imply

$$\begin{aligned}
 A_1 &\cong \left\{ \left(\begin{array}{cc} 0 & \text{Id} \\ 0 & 0 \end{array} \right) \right\}_{\text{span}} \oplus \left\{ \left(\begin{array}{cc} \text{Id} & 0 \\ 0 & -\text{Id} \end{array} \right) \right\}_{\text{span}} \oplus \left\{ \left(\begin{array}{cc} 0 & 0 \\ \text{Id} & 0 \end{array} \right) \right\}_{\text{span}} \\
 &= L_{-2} \oplus \{A(a, b)\}_{\text{span}} \oplus L_2 \\
 \text{Inn Der } U &= \{S(a, b)\}_{\text{span}} \cong G_2 = \text{Dynkin diagram with omitted } \otimes
 \end{aligned}$$

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